Complex dynamics of superconducting neurons

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Θερινό Σχολείο - Συνέδριο

"Δυναμικά Συστήματα & Πολυπλοκότητα"

Outline

- **The Josephson junction**
- Single JJ neuron models
- Coupled JJ neuron models
- JJ neuron dynamics
- Neurocomputational properties
- Motivation & Future work

Josephson junction

Consists of 2 superconductors coupled by a weak link.

- Phase difference: $\phi = \phi_L \phi_R$
- Josephson current-phase relation: $I = I_{\mathbf{Q}} \sin \phi$
- Josephson voltage-phase relation: $V = \frac{\hbar}{2e} \frac{d\phi}{dt}$

Resistively Capacitively Shunted Junction model (RCSJ)

Contributions from displacement and ordinary currents are modelled by the capacitor C and the resistance R.

$$
\ddot{\phi}+\Gamma\dot{\phi}+\sin\phi=i
$$

 $\Phi_0 = h/e$, $\tau^2 = t^2 \Phi_0 C / 2 \pi I_0$, $\Gamma^2 = \Phi_0 / 2 \pi I_0 R^2 C$

RCSJ model

RCLSJ model

For high inductance and low damping: slow–fast dynamics and thus autonomous bursting.

Biological neuron: Fast spiking of Na+ and K+ ions are controlled by a slow process like Ca++ gated K+ ion movement.

S. K. Dana et al., IEEE TRANSACTIONS ON CIRCUITS AND SYSTEMS (2006). E. Neumann and A. Pikovsky, Eur. Phys. J.(2003).

RCLSJ model

SNIC/homoclinic type bursting (Izhikevich)

- Is starts growing \Longrightarrow the junction voltage starts spiking via a SNIC bifurcation
- The spiking amplitude grows until Is starts decaying very slowly
- Is growing rate is much faster than its decay rate
- During the decaying process of Is, the junction voltage also starts decaying in a spiral motion into the saddle focus via a homoclinic bifurcation.

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Resistively coupled RCSJ model

Bursting due to competition between junctions

Nearly complete synchronization for strong coupling

Hongray et al., CHAOS (2015)

Inductively coupled RCSJ model (1)

Dynamics of double-Josephson-junction interferometers^{a)}

James A. Blackburn^{b)}

Physics Department, Wilfrid Laurier University, Waterloo, Ontario, Canada

H. J. T. Smith

Physics Department, University of Waterloo, Waterloo, Ontario, Canada (Received 26 August 1977; accepted for publication 1 December 1977)

Inductively coupled RCSJ model (2)

$$
\ddot{\phi}_p + \Gamma \dot{\phi}_p + \sin \phi_p = -\lambda (\phi_c + \phi_p) + \Lambda_s i_{in} + (1 - \Lambda_p) i_b = i_p
$$

"CONTROL" JJ

$$
\ddot{\phi}_c + \Gamma \dot{\phi}_c + \sin \phi_c = -\lambda (\phi_c + \phi_p) + \Lambda_s i_{in} - \Lambda_p i_b = i_c
$$

$$
\Lambda_s = \frac{L_s}{L_s + L_p}, \quad \Lambda_p = \frac{L_p}{L_s + L_p}
$$

$$
\lambda = \frac{\hbar}{2e(L_s + L_p)I_0}
$$

Crotty et al, "Josephson Junction simulation of neurons", 2010

Inductively coupled RCSJ models

$$
\ddot{\phi}_p + \Gamma \dot{\phi}_p + \sin \phi_p = -\lambda (\phi_c + \phi_p) + \Lambda_s i_{in} + (1 - \Lambda_p) i_b = i_p
$$

$$
\longrightarrow |i_{p} - i_{c} = i_{b}
$$

$$
\ddot{\phi}_c + \Gamma \dot{\phi}_c + \sin \phi_c = -\lambda(\phi_c + \phi_p) + \Lambda_s i_{in} - \Lambda_p i_b = i_c
$$

 Λ _p = 0.5, Λ _s = 0.5, i_b=1.909, Γ = 1.5, λ =0.1, i_{in}=0.22 (t>30)

-20

The JJ neuron mimics the action potential

Dynamics: Excitability

Fixed parameters: $(\Lambda_s, \Lambda_p, \lambda) = (0.5, 0.5, 0.1)$

Rewrite equations:

$$
\dot{\phi}_p = \omega_p
$$

\n
$$
\dot{\omega}_p = -\Gamma \omega - \sin \phi_p - \lambda (\phi_c + \phi_p) + \Lambda_s i_{in} + (1 - \Lambda_p) i_b
$$

\n
$$
\dot{\phi}_c = \omega_c
$$

\n
$$
\dot{\omega}_c = -\Gamma \omega_c - \sin \phi_c - \lambda (\phi_c + \phi_p) + \Lambda_s i_{in} - \Lambda_p i_b,
$$

The fixed points are $(\phi_p^*, 0, \phi_c^*, 0)$ where:

$$
\sin \phi_p^\star - \sin{(-\frac{\sin{\phi_p^\star}}{\lambda} - \phi_p^\star + \frac{\Lambda_s i_{in} + (1-\Lambda_p) i_b}{\lambda})} = i_b \\ \phi_c^\star = -\frac{\sin{\phi_p^\star}}{\lambda} - \phi_p^\star + \frac{\Lambda_s i_{in} + (1-\Lambda_p) i_b}{\lambda}
$$

Number of stable fixed points

position and stability of fixed points independent of Γ

Dynamics: Excitability

Dynamics: Bifurcations and Chaos

D. Chalkiadakis & J. Hizanidis, PRE (2022)

Dynamics: Route to chaos (Γ=0.8)

D. Chalkiadakis & J. Hizanidis, PRE (2022)

Dynamics: mapping of regimes

Neurocomputation properties: **Bursting**

A burst is two or more spikes followed by a period of quiescence. Bursting occurs due to the interplay of fast currents responsible for spiking activity and slow currents that modulate the **activity. In the case of the control of the control of the computational Neuroscience 2007**

In the **bistable regime** small perturbations **ξ(t)** of the stimulus can switch spike trains on and off

 $i_{in}+\xi(t)$

Gaussian white noise with zero mean and autocorrelation function:

$$
\langle \xi(t)\xi(\tau)\rangle = \sigma^2 \delta(t-\tau)
$$

D. Chalkiadakis & J. Hizanidis, PRE (2022)

Neurocomputation properties: **Spike latency**

A barely **superthreshold** stimulation evokes action potentials with a significant **delay.**

Izhikevich, Computational Neuroscience 2007

Long latencies of neuron recorded in vitro of rat motor cortex.

Different JJ neuron implementations

- **Single RCSJ model shows simple spiking**
- Single RCLSJ model shows **bursting** similar to slow-fast ionic mechanism in real neurons
- Resistively coupled RCSJ neurons exhibit **bursting** based on competition of excitable and oscillatory neuron
- Inductively coupled RCSJ neuron (1) shows **bursting** but mechanism has not been studied

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- Inductively coupled RCSJ neuron (1) shows **bursting** but mechanism has not been studied
- Inductively coupled RCSJ neuron (2) mimics the exact neuron-like spiking, bistability, chaos, noise-induced bursting and spike latency

Implementation of a synapse

 $\ddot{\phi}_{p1}+\Gamma \dot{\phi}_{p1}+sin(\phi_{p1})=i_{p1}=-\lambda(\phi_{c1}+\phi_{p1})+\Lambda_{s1}i_{in1}+(1-\Lambda_{p1})i_{b1}-i_{12}-\lambda \frac{v_{out}}{\Lambda_{sm}\omega_{c}^2}$ $\eta \left[\ddot{\phi}_{c1} + \Gamma \dot{\phi}_{c1} + \sin(\phi_{c1}) \right] = i_{c1} = -\lambda(\phi_{c1} + \phi_{p1}) + \Lambda_{s1} i_{in1} - \Lambda_{p1} i_{b1}$

 $\ddot{\phi}_{p2}+\Gamma\dot{\phi}_{p2}+sin(\phi_{p2})=i_{p2}=-\lambda(\phi_{c2}+\phi_{p2})+\Lambda_{s2}i_{12}+(1-\Lambda_{p2})i_{b2}$ $\eta \left[\ddot{\phi}_{c2} + \Gamma \dot{\phi}_{c2} + \sin(\phi_{c2}) \right] = i_{c2} = -\lambda(\phi_{c2} + \phi_{p2}) + \Lambda_{s2} i_{12} - \Lambda_n i_{b2}$

$$
\begin{array}{l} \frac{1}{\Omega_0^2}\ddot{\upsilon}_{out}+\frac{Q}{\Omega_0}\dot{\upsilon}_{out}+\upsilon_{out}=\upsilon_p-\frac{Q\Omega_0\Lambda_{syn}}{\lambda}i_{12}-\frac{\Lambda_{syn}}{\lambda}\dot{i}_{12}\\ \frac{\Lambda_{syn}(1-\Lambda_{syn})}{\lambda}\dot{i}_{12}+\frac{r_{12}}{\Gamma}\dot{i}_{12}=\upsilon_{out}-\Lambda_{syn}(\dot{\phi}_{c2}+\dot{\phi}_{p2})\end{array}
$$

The output is taken across the capacitor and sent through a resistor to the input of a postsynaptic neuron.

If the bias current applied to the JJ neuron is positive (negative) with respect to ground, then the synapse is excitatory (inhibitory).

- **Desynchronization**
- In-phase & anti-phase synchronization

Segall et al, "Synchronization dynamics on the picosecond time scale in coupled Josephson junction neurons", PRE (2017).

"SuperMind: a survey of the potential of superconducting electronics for neuromorphic computing", Schneider et al, Supercond. Sci. Technol. (2022).

Brains have been inspiring computers for decades

John von Neumann Mann Alan Turing

Neuromorphic Electronic Systems

CARVER MEAD

Invited Paper

PROCEEDINGS OF THE IEEE, VOL. 78, NO. 10, OCTOBER 1990

Motivation behind Neuromorphic Computing

The parrot's brain far outperforms today's state-of-the-art computer architectures (in speed, weight, power) by orders of magnitude.

Architecture All Access: Neuromorphic Computing (Intel Technology)

neurons $(-10¹¹)$ & synapses $(-10¹⁵)$ transistor area and wiring ~10.000 synapses per neuron resources are behind many

plasticity due to adaptive synapses and all imited reconfigurability

operation speeds: ms, kHz ns, GHz very fast

Brain vs Conventional Computer

co-location of memory & processing memory and computing are separate ("von Neumann bottleneck")

orders of magnitude

stochasticity of cells, low energy **high-precisions reliable circuits**

Existing neuromorphic machines

TrueNorth Chip (IBM)

Machine learning applications (image recognition)

Loihi 2 (Intel)

1 million neurons per chip Applications: robotic skin with a sense of touch National University of Singapore (NUS)

Different neuromorphic systems: comparison

Josephson Junctions

Danijela Marković et al. "Physics for neuromorphic computing", Nature Reviews (2020)

High Performance Computing applications

IBM quantum computer

Once you are working cryogenically already for Quantum Computing, why not build extra neuromorphic devices using **superconductors**?

Neuromorphic computing: two approaches

- 1. **Map AI algorithms to physical systems**: Develop hardware (beyond GPUs and TPUs) that is better suited to run current neural networks (physical reservoir computing)
- 2. **Match neuroscience-inspired concepts to hardware and software**:

Implement neural networks that spike (SNNs), feature memory, are stochastic, can oscillate and synchronize (plasticity), are excitable, exhibit bursting, and chaos….

DYNAMICS & COMPLEXITY

Work in progress and future ideas

- Dynamical properties and synchronization of bursting patterns in coupled RCLS neurons (model 1) (with ECE AUTH student Giorgos Baxevanis)
- Study of JJ autapse known to be responsible for excitability switching
- Reservoir computing with JJ neurons/autapse (collaborator: Prof. Kathy Luedge TU Ilmenau, Germany)

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